

OFFSET VOLTAGES (CURRENTS)



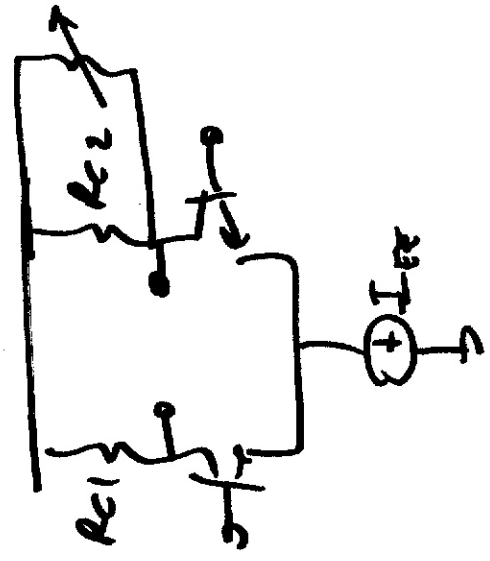
OFFSET VOLTAGE DUE TO MISMATCHES

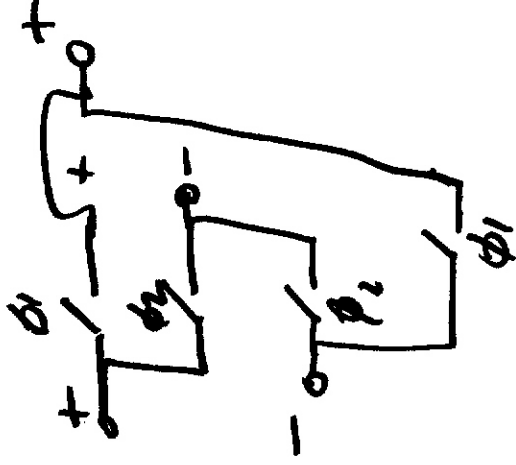
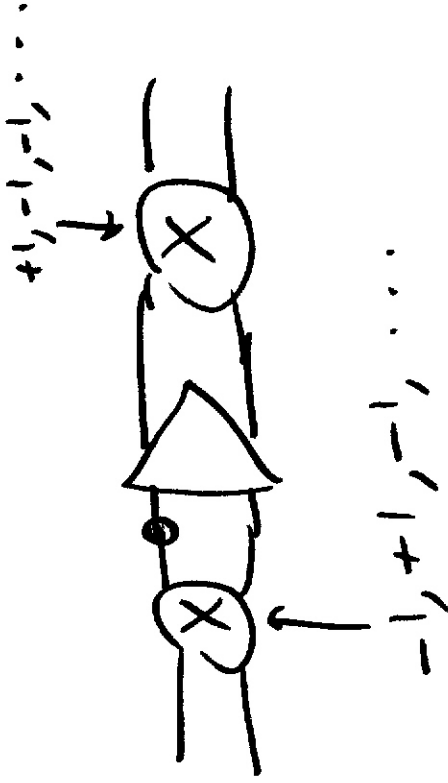


ZERO-OFFSET AMP

OFFSET VOLTAGE (INPUT REF)

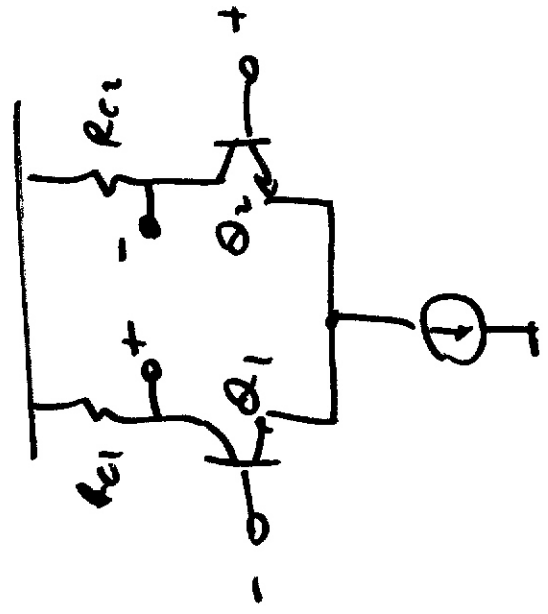
SOLUTIONS: - TRIM OFFSET





$$R_c = \frac{R_{c1} + R_{c2}}{2} \quad I_S = \frac{I_{S1} + I_{S2}}{2}$$

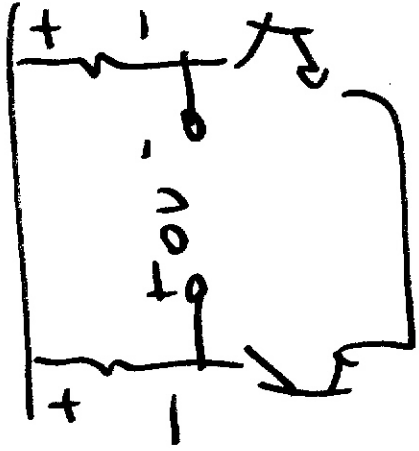
$$\Delta R_c = R_{c1} - R_{c2} \quad \Delta I_S$$



$$v^+ - v^- = v_{BE2} - v_{BE1}$$

$$= \frac{kT}{q} \left( \ln \frac{I_{C2}}{I_{S2}} - \ln \frac{I_{C1}}{I_{S1}} \right)$$

$$V_{d,i} = \frac{kT}{q} \left( \ln \frac{I_{C2}}{I_{C1}} + \ln \frac{I_{S1}}{I_{S2}} \right)$$



$$I_{C1} \cdot R_{C1} = I_{C2} \cdot R_{C2}$$

$$\frac{I_{C1}}{I_{C2}} = \frac{R_{C2}}{R_{C1}}$$

$$V_{OS} = \frac{kT}{q} \left\{ \ln \left( \frac{R_{C1}}{R_{C2}} \right) + \ln \left( \frac{I_{S1}}{I_{S2}} \right) \right\}$$

$$= \frac{kT}{q} \left[ \ln \left( \frac{R_C + \frac{\Delta R_C}{2}}{R_C - \frac{\Delta R_C}{2}} \right) + \ln \left( \frac{I_S + \frac{\Delta I_S}{2}}{I_S - \frac{\Delta I_S}{2}} \right) \right]$$

$$= \frac{kT}{q} \left\{ \ln \left( \frac{1 + \frac{\Delta R_C}{2}}{1 - \frac{\Delta R_C}{2}} \right) + \ln \left( \right) \right\}$$

$$\ln \left( \left( 1 + \frac{\Delta R_C}{2} \right) \left( 1 + \frac{\Delta R_C}{2} \right) \right) + \ln \left( \right)$$

$$V_{OS} = \frac{kT}{q} \left\{ \ln(1 + \frac{\Delta R_C}{R_C}) + \ln(1 + \frac{\Delta I_S}{I_S}) \right\}$$

$$\ln(1 + \delta) \approx \delta$$

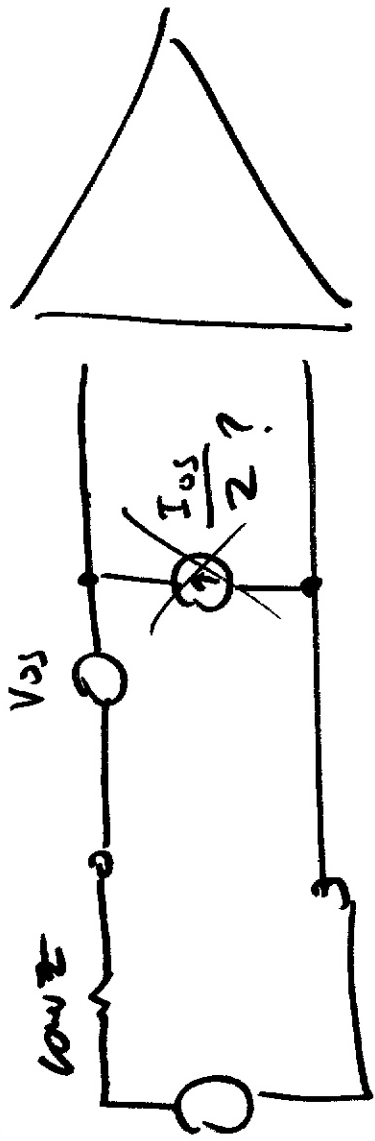
$$V_{OS} = \left( \frac{kT}{q} \right) \left\{ \frac{\Delta R_C}{R_C} + \frac{\Delta I_S}{I_S} \right\}$$

$$= 25 \text{ mV} \left( \underbrace{\left| \frac{\Delta R_C}{R_C} \right|}_{1\%} + \underbrace{\left| \frac{\Delta I_S}{I_S} \right|}_{5\%} \right) = 1.5 \text{ mV}$$

$$\sigma_{V_{OS}}^2 = \left( \frac{kT}{q} \right)^2 \left( \sigma_{\frac{\Delta R_C}{R_C}}^2 + \sigma_{\frac{\Delta I_S}{I_S}}^2 \right)$$

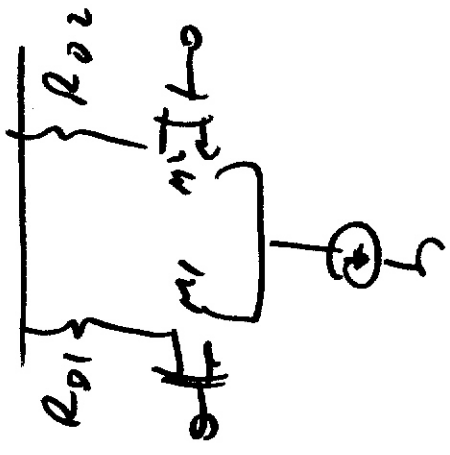
$$= \sqrt{(25 \text{ mV})^2 (1\%)^2 + (25 \text{ mV})^2 (5\%)^2} = 1.3 \text{ mV}$$

CURRENT OFFSET ?  $\beta$  MISMATCH  $\Rightarrow$



MOSFET OFFSET

$I_{D1} R_{D1} = I_{D2} R_{D2}$   
 TRIM CONDITION!



$$V_{id} = V_{GS1} - V_{GS2}$$

$$= V_{T1} + \sqrt{\frac{2I_{D1}}{\mu_{COX}(\frac{W}{L})_1}} - V_{T2} - \sqrt{\frac{2I_{D2}}{\mu_{COX}(\frac{W}{L})_2}}$$

$$V_{os} = \Delta V_T + \sqrt{\mu_{os} \left( \frac{2I_D}{2I_D} \right)} \left( \sqrt{\frac{1 - \frac{\Delta I_D}{2I_D}}{1 - \frac{\Delta V_T}{2V_T}}} - \sqrt{\frac{1 + \dots}{1 + \dots}} \right)$$

$$= \Delta V_T + V_{os} \left( \sqrt{\left(1 - \frac{\Delta I_D}{2I_D}\right) \left(1 + \frac{\Delta V_T}{2V_T}\right)} - \sqrt{\dots} \right)$$

$$\left( \sqrt{1 - \frac{\Delta I_D}{2I_D} + \frac{\Delta V_T}{2V_T}} - \sqrt{\dots} \right)$$

$$\sqrt{1 + \delta} = 1 + \frac{1}{2}\delta$$

$$= 1 - \frac{\Delta I_D}{4I_D} + \frac{\Delta V_T}{4V_T} - 1 - \frac{\Delta I_D}{4I_D} + \dots$$

$$V_{os} = \Delta V_T + \frac{V_{os}}{2} \left( -\frac{\Delta I_D}{I_D} + \frac{\Delta V_T}{V_T} \right)$$

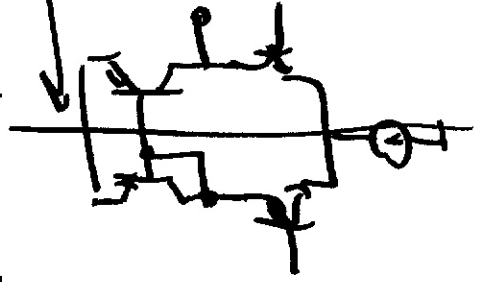
$$\frac{\Delta I_D}{I_D} = - \frac{\Delta R_D}{R_D}$$

$$V_{GS} = \Delta V_T + \frac{V_{DD}}{2} \left( \frac{\Delta R_D}{R_D} + \frac{\Delta V_T}{V_{DD}} \right)$$

$\uparrow$   $\sim 10\text{mV}$   $\uparrow$   $\sim 100\text{mV}$   
 LAYOUT  $\sim 1\text{mV}$

MOSFETS HAVE INHERENT OFFSET CURRENTS!

BUT MUCH SMALLER OFFSET CURRENTS!  
 NOT SYMMETRIC!



SYSTEMATIC OFFSET

SETTING TIME

DYNAMIC ERRORS

Q

STATIC ERROR ← FINITE GAIN



$$0 = (V_x - V_i) s C_s + V_x s C_p + (V_x - V_0) s C_F = 0$$

$$V_x (C_s + C_p + C_F) = V_i \beta C_s + V_0 C_F$$

$$V_x = F \cdot V_0 + F \cdot \frac{C_s}{C_F} \cdot V_i$$

$$\frac{-V_0}{F A V} = F \cdot V_0 + F \cdot \frac{C_s}{C_F} \cdot V_i$$

ORIGIN OF ERROR TERM!

$$F = \frac{C_F}{C_s + C_p + C_F}$$



$$\frac{V_o}{V_i} = \frac{-\frac{C_s}{C_F}}{\frac{1}{A_v \cdot F} + 1} = \frac{C}{1 + \underbrace{\frac{1}{A_v \cdot F}}_T} \quad \text{LOOP GAIN}$$

$$\approx C \left( 1 - \frac{1}{T} \right)$$

RELATIVE ERROR  
 $\Rightarrow$  STATIC ERROR

$A_v$  : LARGE SIGNAL GAIN

EX CLOSED LOOP GAIN =  $-4 = C$

$$C_F = 1PF \quad C_S = 4PF \quad C_P = 1PF$$

$$F = \frac{C_F}{C_F + C_S + C_P} = \frac{1}{6}$$

$C_P$  DOES HURT US!  $F \neq 1/C$

ERROR  $< 0.1\%$

$$\frac{1}{F A_v} < 0.1\%$$

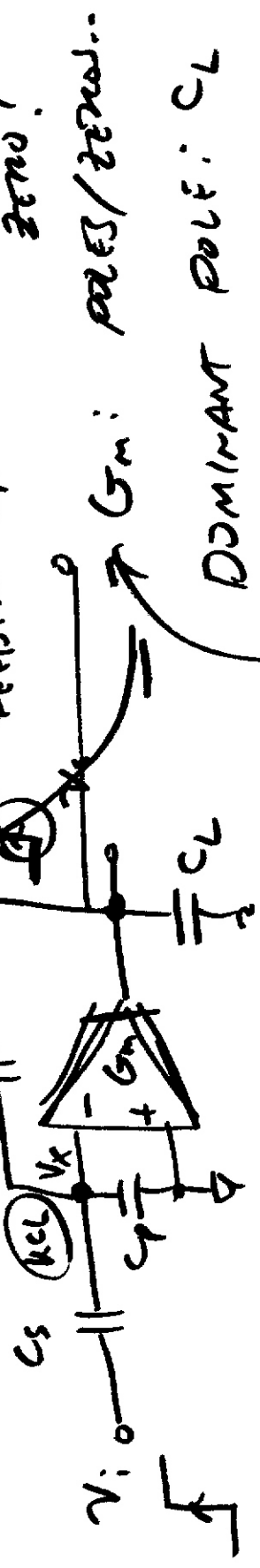
$$F A_v > 1000$$

$A_v > 6000$
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OVER THE DESIRED  
OIP RANGE!

DYNAMIC ERRORS : LINEAR SETTLING

FOR FEEDBACK CF : FEED FORWARD ZERO!



DOMINANT POLY: CL

NON-DOMINANT POLES

$$v_x (C_S + C_F + C_P) = v_i C_S + v_o C_F$$

$$v_x = \frac{C_S \cdot F \cdot v_i + F \cdot v_o}{C_F}$$

$$v_o s C_L + G_m v_x + (v_i - v_x) s C_F = 0$$

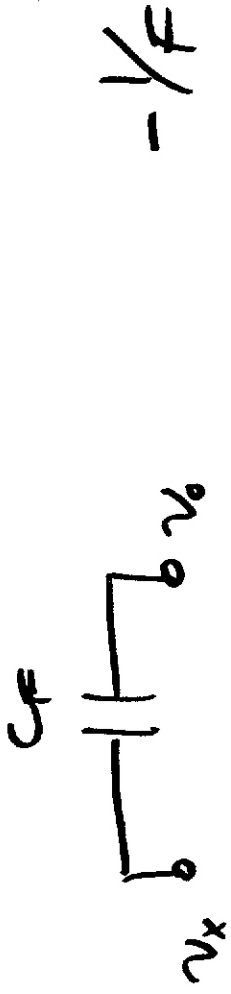
$$v_o s (C_L + C_F) = v_x (s C_F - G_m)$$

$$\frac{v_o}{v_i} = \frac{\frac{C_S}{C_F} F (s C_F - G_m)}{F G_m + s (C_L + C_F (1-F))}$$

$$= \frac{\left(-\frac{C_S}{C_F}\right) F \cancel{G_m} \left(1 - \frac{s C_F}{G_m}\right)}{\cancel{F G_m} \left(1 + s \frac{C_L + C_F (1-F)}{F G_m}\right)}$$

$$= \frac{\left(-\frac{C_S}{C_F}\right) \left(1 - \frac{s}{z}\right)}{\left(1 + \frac{s}{p}\right)}$$

$$z = \frac{G_m}{C_F} \quad p = \frac{F G_m}{C_L + C_F (1-F)} = \frac{F G_m}{C_{L,eff}} \rightarrow$$



|||



$$C_1 = C_F (1 - A_V) = C_F (1 + 1/F)$$

$$C_2 = C_F (1 - 1/A_V) = \underbrace{C_F (1 - F)}_{\text{MILLER CAP}}$$

MILLER CAP

## STEP RESPONSE :

$$H(s) = C \frac{(1 - s/2)}{(1 + s/p)}$$

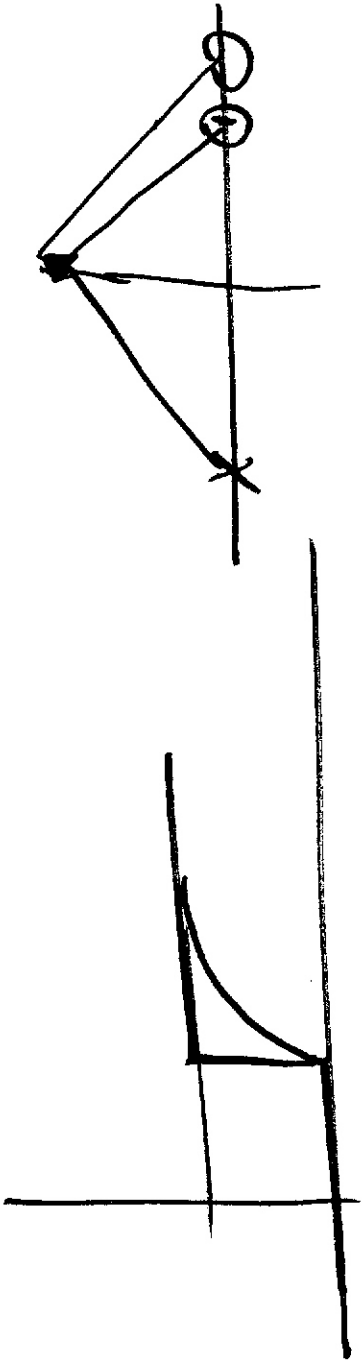
RHP ZERO                      LHP POLE

$$v_o(t) = \mathcal{L}^{-1} \left\{ H(s) \cdot \frac{V_{in}}{s} \right\}$$

$$= -V_{in} |k| \left\{ 1 - \underbrace{\left(1 + \frac{p}{2}\right) e^{pt}} \right\}$$

~~Dynamic Error Term~~  
DYNAMIC ERROR TERM

TIME CONSTANT  $1/p = \tau = \frac{C_{eff}}{F \cdot G_m}$



$$\left(\frac{P}{2}\right) = -F \frac{c_F}{c_{left}} = -1$$

$$\begin{aligned} v_0(t) &= -v_{in}(c) \left\{ 1 - 1 - (P+\varepsilon) e^{Pt} \right\} \\ &= -v_{in}(c) \left\{ 1 - \varepsilon e^{Pt} \right\} \end{aligned}$$