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Lecture 6: Noise Analysis Lecture 6: Noise Analysis

Ali M. Niknejad and Bernhard E. Boser © 2006

Department of Electrical Engineering and Computer Sciences

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Input Equivalent Noise Input Equivalent Noise

- Two-port representation
- Fictitious noise sources
- Effect of source resistance
- Correlation

Equivalent Noise Generators Equivalent Noise Generators

- \bullet Any noisy two port can be replaced with a *noiseless* two-port and equivalent input noise sources
- In general, these noise sources are correlated. For now let's neglect the correlation.

Finding the Equivalent Generators Finding the Equivalent Generators

- \bullet The equivalent sources are found by opening and shorting the input and equating the noise.
- • For a shorted input, the input current flows through the short and the output is due only to the input noise.
- \bullet For an open input, the dangling voltage does not contribute to the output noise.

Role of Source Resistance Role of Source Resistance

- If $R_s = 0$, only the voltage noise v_n is important. Likewise, if $R_s = \infty$, only the current noise i_n is important.
- Amplifier Selection: If R_s is large, then select an amp with low i_n (MOS). If R_s is low, pick an amp with low v_n (BJT).
- For a given R_s , there is an optimal v_n/i_n ratio.
- •Alternatively, for a given amp, there is an optimal *R s.*

Total Output Noise Total Output Noise

$$
\overline{v_o^2} = (\overline{v_n^2} A_v^2 + \overline{v_{R_s}^2} A_v^2) \left(\frac{R_{in}}{R_{in} + R_s}\right)^2 + \left(\frac{R_{in}}{R_{in} + R_s}\right)^2 R_s^2 \overline{i_n^2} A_v^2
$$

$$
= (\overline{v_n^2} + \overline{i_n^2} R_s^2 + \overline{v_{R_s}^2}) \left(\frac{R_{in}}{R_{in} + R_s}\right)^2 A_v^2
$$

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New Equivalent Generator New Equivalent Generator

- We see that the total noise can be lumped into one equivalent voltage once *R s* is known.
- Be careful! Up to now we ignored the correlation.

Optimum Source Impedance Optimum Source Impedance

$$
R_{opt} = \sqrt{\frac{R_n}{G_n}} = \sqrt{\frac{v_n^2}{i_n^2}}
$$

• For a given two-port (amplifier), what's the optimum source impedance? Find the total output noise and find the minima for *R s* to find *Ropt*.

Correlated Noise Sources Correlated Noise Sources

• Let's partition the input noise current into two components, a component correlated ("parallel") to the noise voltage and a component uncorrelated ("perpendicular") of the noise voltage

$$
i_n = i_c + i_u
$$

$$
\langle i_u, v_n \rangle = 0 \qquad \qquad i_c = Y_C v_n
$$

$$
v_{eq} = v_n(1 + Y_C Z_S) + Z_S i_u
$$

Equivalent Noise Voltage (Equivalent Noise Voltage (cor)

• Since the above expression is the sum of two uncorrelated noise voltages, we have

$$
\overline{v_{eq}^2} = \overline{v_n^2} |1 + Y_C Z_S|^2 + |Z_s|^2 \overline{i_u^2}
$$

• Now we can continue as before to find $B_{opt} = B_s = -B_c$

$$
G_{opt} = G_s = \sqrt{\frac{G_u}{R_n} + G_c^2}
$$

Noise and Feedback Noise and Feedback

- • Ideal feedback:
	- No increase of input referred noise
	- No decrease of SNR at output
- \bullet Practical feedback: increased noise
	- Noise from feedback network
	- Noise gain from elements outside feedback loop
- • System level: feedback can mitigate noise problems
	- E.g. under-damped accelerometer Ref: M. Lemkin and B. E. Boser, "A Three-Axis Micromachined Accelerometer with a CMOS Position-Sense Interface and Digital Offset-Trim Electronics," *IEEE J. Solid-State Circuits*, vol. SC-34, pp. 456-468, April 1999.

Ideal Feedback Ideal Feedback

Order of summation irrelevant:

 \rightarrow Circuits are identical

Ideal Feedback and Noise Ideal Feedback and Noise

• It's clear that the ideal feedback network does not alter the noise of the system. Real feedback elements, though, have noise.

Example: Shunt Feedback Example: Shunt Feedback

- • Shunt feedback samples the output voltage and subtracts from the input current. It's thus most effective in a trans-resistance amplifier configuration.
- The action of the feedback is to lower the input and output impedance. In a typical implementation, the resistor R_F adds thermal noise to the input.

Shunt FB Analysis Shunt FB Analysis W. ۸N R_F R_F $\overline{v_i^2}$ $\overline{v_n^2}$ **444** $^{+}$ $\overline{i^2}$ $\overline{i^2}$ v_o v_{α}

- To find the equiv input noise voltage, we short the input (and thus the noise current).
- The output noise is clearly given by the two-port voltage gain squared. Even though we don't think of this as a voltage amplifier, we can still use the trans-resistance gain since $i_{in} = v_{in}/Z_{in}$

Shunt FB Equiv Voltage Noise Shunt FB Equiv Voltage Noise

$$
\overline{v_o^2} = \overline{v_i^2} |A_v|^2 \quad \Bigg\} \quad \overline{v_i^2} = \overline{v_n^2}
$$

$$
\overline{v_o^2} = \overline{v_n^2} |A_v|^2 \quad \Bigg\}
$$

- The *voltage gain* does not change with feedback since we are voltage driving the circuit.
- Since the input current is independent of the feedback noise current, it does not alter the output noise.

Shunt FB Equiv Noise Current Shunt FB Equiv Noise Current

• If we leave the input terminal open-circuited, then the input voltage noise for the equiv circuit is disabled. For the real circuit, though, the input noise is active through R_F .

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Shunt Noise Current Shunt Noise Current

• Suppose the closed-loop gain of the circuit is given by $Z_{cl} \approx R_{F}$. Then we have

$$
\overline{v_o^2} = |Z_{cl}|^2 \overline{i_i^2}
$$

• For the full circuit, let α represent the input current division between the two-port and the feedback network. If the two-port output imepdance is small, we have $\alpha = Z_{\text{in}}/(Z_{\text{in}} + R_{\text{F}}) \approx 1$ $\overline{v_o^2} = |Z_{cl}|^2 \overline{i_{ia}^2} |\alpha|^2 + \overline{i_F^2} |Z_{cl}|^2 |\alpha|^2 + \frac{\overline{v_{ia}^2}}{R_{\overline{z}}^2} |Z_{cl}|^2$

Shunt Current (cont)

• The first two terms are pretty obvious. The last term requires a small calculation as shown below

$$
v_o = Gi_{in} = G \frac{v_o - v_{ia}}{R_F + Z_{in}}
$$

$$
v_o(1 - \frac{G}{R_F + Z_{in}}) = -G \frac{v_{ia}}{R_F + Z_{in}}
$$

$$
v_o = -\frac{G}{1 + T} \frac{v_{ia}}{R_F + Z_{in}} \approx -Z_{cl} \frac{v_{ia}}{R_F}
$$

Series-Shunt Feedback

• In a feedback voltage amplifier, opencircuit the input to find the equivalent input noise. It's clear from the above figure that

$$
\overline{i_i^2} = \overline{i_n^2}
$$

Series -Shunt Shorted Input

- Assuming high/low input/output impedance, the current i_n develops a voltage across $\rm R_E||R_F.$
- The noise voltages due to R_E and R_F generate an input that is readily calculated by voltage division.

Series -Shunt Noise Voltage Shunt Noise Voltage

• We compute the transfer function from each noise source to the output using superposition. Let A_{cl} represent the closedloop voltage gain

$$
\overline{v_o^2} = |A_{cl}|^2 \left\{ \overline{v_{ia}^2} + \overline{i_{ia}^2} R_E || R_F + \left(\frac{R_F}{R_E + R_F}\right)^2 \overline{v_{R_E}^2} + \left(\frac{R_E}{R_E + R_F}\right)^2 \overline{v_{R_F}^2} + \right\}
$$

• The above can be simplified to

$$
\overline{v_o^2} = |A_{cl}|^2 \left\{ \overline{v_{ia}^2} + \overline{i_{ia}^2} (R_E || R_F) + 4kt \Delta f(R_E || R_F) \right\}
$$

Series -Shunt Voltage (cont)

• Since the same closed-loop gain is used for the equivalent noise generator, we have

$$
\overline{v_i^2} = \overline{v_{ia}^2} + \overline{i_{ia}^2}(R_E||R_F) + 4kt\Delta f(R_E||R_F)
$$

• If the loop gain and closed-loop gain is large, we have

$$
A_{cl} \approx \frac{1}{f} = 1 + \frac{R_F}{R_E} \gg 1
$$

• Which means that the noise of R_E dominates.

Feedback Summary Feedback Summary

- For quick approximations, simply consider the loading effect of the feedback network on the input and associate a noise to this element.
- For shunt-shunt feedback, the loading at the input is R_F . Since the input is a current, represent this as an input noise current.
- For series-shunt feedback, the loading is $R_{\rm F}$ || $R_{\rm E}$ (short the output). Since the input is a voltage, we associate a noise voltage with this element.

Example: Non-Inverting Amp

Example:

$$
R_1 = R_o (A_{v0} - 1)
$$

\n
$$
R_2 = R_o = 100 \text{k}\Omega
$$

\n
$$
A_{v0} = 10
$$

\n
$$
\frac{v_{n\text{fb}}^2}{\Delta f} = \left(40 \frac{\text{nV}}{\sqrt{\text{Hz}}} \right)^2
$$

 \bullet Decreasing R_0 reduces noise but increases feedback current

Example: Inverting Amplifier

$$
v_o = -v_i \frac{R_2}{R_1} + v_n \frac{R_1 + R_2}{R_1}
$$

$$
\overline{v_{\text{ieq}}^2} = \overline{v_n^2} \left(\frac{R_1 + R_2}{R_1} \frac{R_1}{R_2} \right)^2
$$

$$
= \overline{v_n^2} \left(\frac{R_1 + R_2}{R_2} \right)^2
$$

$$
= \overline{v^2} \left(1 + \frac{1}{\sqrt{1 - \frac{1}{n^2}}} \right)^2
$$

Example:

$$
A_{v0} = -1: \qquad \sqrt{\frac{v_{ieg}^2}{v_n^2}} = 2
$$

$$
A_{v0} = -10: \qquad \sqrt{\frac{v_{ieg}^2}{v_n^2}} = 1.1
$$

$$
A_{v0} = -0.1: \qquad \sqrt{\frac{v_{ieg}^2}{v_n^2}} = 11
$$

Noise from R_1 , R_2 ignored.

<u>Note</u>: R_{1} is outside feedback loop \rightarrow signal and noise have different gains to output.

$$
\overline{v_{ieq}^2 \neq v_n^2}
$$

 $1+\frac{1}{\vert A \vert}$

 $\overline{}$

 $= v_{n}^{-}$ | 1+

v

 \setminus

 $\left| \begin{array}{c} \n\cdot \cdot \cdot \n\end{array} \right| A$

0

v

 \int

Example: MOS S&H Example: MOS S&H

• Sampling noise:

$$
\overline{v_{on}^{2}(f)} = 4k_{B}TR \left| \frac{1}{1 + sRC} \right|^{2}
$$

$$
\overline{v_{or}^{2}} = \int_{0}^{\infty} \overline{v_{on}^{2}(f)} df
$$

$$
= \frac{k_{B}T}{C}
$$

• Noise bandwidth:

$$
4k_BTRB = \frac{k_B T}{C}
$$

$$
B = \frac{1}{4RC} = \frac{\pi}{2} f_o
$$
 with f_c

with

 o 2πRC $=$ $\frac{1}{}$

Sampling Noise Sampling Noise

- KT/C " noise
- Application: ADC, SC circuits, ...
- Aliasing
- Variance of noise sample
- Spectral density of sampled noise

SPICE Verification SPICE Verification

Useful Integrals Useful Integrals

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Example 4: CS Amplifier

$$
\overline{v_{on}^{2}(f)} = 4k_{B}T\left(\frac{1}{R_{L}} + \frac{2}{3}g_{m}\right)\frac{R_{L}}{1 + sR_{L}C_{L}}^{2}
$$
\n
$$
\overline{v_{or}^{2}} = 4k_{B}T\left(\frac{1}{R_{L}} + \frac{2}{3}g_{m}\right)R_{L}^{2}\int_{0}^{\infty}\frac{1}{1 + sR_{L}C_{L}}^{2} df
$$
\n
$$
= 4k_{B}T\left(\frac{1}{R_{L}} + \frac{2}{3}g_{m}\right)R_{L}^{2}\frac{1}{4R_{L}C_{L}}
$$
\n
$$
= \frac{k_{B}T}{C_{L}}\left(1 + \frac{2}{3}g_{m}R_{L}\right)
$$
\n
$$
= \frac{k_{B}T}{C_{L}}\left(1 + \frac{2}{3}|A_{vo}|\right)
$$
\n
$$
= \frac{k_{B}T}{C_{L}}n_{F}
$$

SPICE Circuit SPICE Circuit

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SPICE Result SPICE Result

Signal -To -Noise Ratio Noise Ratio

- SNR*noisesig P* $SNR = \frac{P_s}{P}$
- \bullet Signal Power sinusoidal source

$$
P_{sig} = \frac{1}{2} V_{zero-peak}^2
$$

 $P_{noise} = \frac{k_B T}{\sqrt{2}}$

$$
P_{\rm sig}=0.5 V^2
$$

$$
P_{noise} = (64 \,\mu V)^2
$$

• Noise Power assuming thermal noise dominates $\frac{D}{D_{noise}} = \frac{n_B T}{C} n$

$$
SNR = \frac{0.5}{(64\,\mu)^2} = 122 \times 10^6 = 80.9 dB
$$

f

• $SNR = f(C)$

$$
C \qquad \uparrow \times 4 \qquad \qquad SNR \qquad \uparrow +6dB
$$

dB versus Bits dB versus Bits

- Quantization "noise"
	- –Quantizer step size: Δ
	- –Box-car pdf
	- Variance:

$$
S_Q = \frac{\Delta^2}{12}
$$

- SNR of N-Bit sinusoidal signal
	- –Signal power

– SNR

$$
P_{sig} = \frac{1}{2} \left(2^N \frac{\Delta}{2} \right)^2
$$

 $=\frac{1 \text{ sig}}{1.5 \times 10^{14}} = 1.5 \times$

S

Q

 $SNR = \frac{P_s}{P}$

$$
= [1.76 + 6.02N] \text{ dB}
$$

 1.5×2

 \sim

2

N

6.02 dB per Bit

SNR versus Power SNR versus Power

- \bullet 1 Bit \rightarrow 6dB \rightarrow 4x SNR
- $4x$ SNR \rightarrow $4x$ C
- Circuit bandwidth $\sim g_{\rm m}/C$ \rightarrow 4x $g_{\rm m}$
- \bullet Keeping V* constant \rightarrow 4x I_D, 4x W
- \bullet Thermal noise limited circuit:Each additional Bit QUADRUPLES power dissipation. E.g. 15 Bit noise-limited ADC dissipates 100mW 16 Bit redesign dissipates 400mW !
- •Overdesign is very costly. We need design procedures that get us very close to the specifications.

Analog Circuit Dynamic Range Analog Circuit Dynamic Range

• The biggest signal we can ever expect at the output of a circuit is limited by the supply voltage, V_{DD} . Hence (for sinusoids)

$$
V_{\text{max}}(rms) = \frac{1}{\sqrt{2}} \frac{V_{DD}}{2}
$$

•The noise is

$$
V_n(rms) = \sqrt{n_f \frac{k_B T}{C}}
$$

•So the dynamic range in dB is:

$$
DR = \frac{V_{\text{max}}(rms)}{V_n(rms)} = \frac{V_{DD}\sqrt{C}}{\sqrt{8n_f k_B T}}
$$
 [V/V]
= $20\log_{10}\left(V_{DD}\sqrt{\frac{C}{n_f}}\right) + 75$ [dB] with C in [pF]

Analog Circuit Dynamic Range Analog Circuit Dynamic Range

- \bullet For integrated circuits built in modern CMOS processes, V_{DD} < 3V and C \langle 1nF (n_f = 1)
	- DR < 110dB (18 Bits)
- \bullet For PC board circuits built with "old-fashioned" 30V opamps and discrete capacitors of < 100nF
	- DR < 140dB (23 Bits)
	- A 30dB (5 Bit) advantage!
- •Note: oversampling ADCs break this barrier (cost: speed penalty)

"Big " Noise Example Noise Example

- • Cascoded common-source stage: what are the noise contributions from M1, M2?
- • Simplified model for conclusive results:
	- Lump parasitic capacitors
	- Feedback sets gain, neglect r_o

Calculate noise transfer functions to amplifier output:

$$
v_o: \quad s(C_L + C_F)v_o - sC_Fv_g - g_{m2}v_x + i_{n2} = 0
$$

\n
$$
v_x: \quad sC_xv_x + g_{m1}v_g + g_{m2}v_x + i_{n1} - i_{n2} = 0
$$

\n
$$
v_g: \quad v_g = Fv_o
$$

\nwith
$$
F = \frac{C_F}{C_F + C_S + C_P}
$$

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After some algebra …

$$
\omega_p = \frac{g_{m2}}{C_x}
$$

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Spectral noise density at amplifier output:

$$
\frac{\overline{v_{on}^2}}{\Delta f} = \frac{4k_b T}{F^2 g_{m1}} \left(\frac{1}{\mu_1} + \frac{g_{m2}}{g_{m1}} \left| \frac{s}{\omega_p} \right|^2 \right) \left| \frac{1}{1 + \frac{s}{\omega_o Q} + \frac{s^2}{\omega_o^2}} \right|^2
$$

- • Noise from M2:
	- Circular current at low frequency \rightarrow does not reach amplifier output
	- $\;$ At high frequency $\mathsf{C}_\mathsf{x}\to\mathsf{short}$
- • **Cascode contributes little noise at low frequency**
- • **At high frequency the noise contribution can be significant**

0

$$
\int_{0}^{\infty} \frac{\overline{v}_{on}^{2}(f)}{\Delta f} df = \frac{4k_{b}T\gamma}{F^{2}g_{m1}} \int_{0}^{\infty} df \left[\frac{1}{\mu_{1}} + \frac{g_{m2}}{g_{m1}} \left| \frac{s}{\omega_{p}} \right|^{2} \right] + \frac{s}{\omega_{0}Q} + \frac{s^{2}}{\omega_{0}^{2}} \right]
$$
\n
$$
= \frac{4k_{b}T\gamma}{F^{2}g_{m1}} \frac{\omega_{0}Q}{4} \left[1 + \frac{g_{m2}}{g_{m1}} \left(\frac{\omega_{0}}{\omega_{p}} \right)^{2} \right]
$$
\n
$$
= \frac{k_{b}T\gamma}{F C_{Leff}} \left(1 + \frac{g_{m2}}{g_{m1}} \frac{\omega_{u}}{\omega_{p}} \right)
$$
\n
$$
= \frac{k_{b}T\gamma}{F C_{Leff}} \left(1 + \frac{g_{m2}}{g_{m1}} \frac{\omega_{u}}{\omega_{p}} \right)
$$
\n
$$
= \frac{k_{b}T\gamma}{F C_{Leff}} \left[\frac{1}{\mu_{1}} + \frac{FC_{x}}{C_{Leff}} \right]
$$

- **Total noise depends only on C!**
- **M1 always contributes noise**
- **Significant noise from M2 for "large" C x**
	- \rightarrow make C_x small (compared to C_{Leff})

Design Example Design Example

- Track & Hold amplifier for 16-Bit ADC (B=16)
- $f_s = 100MHz \rightarrow \omega_u \sim 2\pi f_s N$ $N = \ln(2^B)$... based on settling, see later
- Amplifier based on cascoded common-source, $A_v = -1$
- \bullet Choose
	- $-$ L = 0.35 μ m
	- –M1 and M2 same size (not necessarily ideal)
	- $C_F = C_S = C_{GS}$ (reasonable tradeoff) \rightarrow F = 1/3
	- –Maximum signal amplitude V_s (peak-to-peak)

Design Equations Design Equations

$$
DR = (2B)2
$$

\n
$$
= \frac{\frac{1}{2} \left(\frac{V_s}{2}\right)^2}{\frac{kT}{FC_{Leff}} \left(1 + \frac{C_x \approx C_{GS}}{C_{Leff}}\right)}
$$

\n
$$
\omega_u = 2\pi f_s N
$$

\n
$$
= F \frac{g_{m1}}{C_{Leff}}
$$

\n
$$
C_{GS} = \frac{2}{3}WLC_{ox}
$$

\n
$$
V^* = \frac{2I_D}{g_{m1}}
$$

\n
$$
V^* = \frac{2I_D}{g_{m1}}
$$

\n
$$
V^* = \frac{2I_D}{G_{m1}}
$$

Design Examples Design Examples

