University of California, Berkeley EECS 240 Spring 2006 Prof. A. Niknejad

#### Problem Set 5 Solutions

1. The offset voltage Vos of an amplifier is defined as the input required to satisfy  $V_o = 0$ V. Calculate the variance of the offset voltage of the differential amplifier below as a function of  $\sigma_{V_th}$ ,  $\sigma_{\frac{\Delta R}{R}}$ ,  $I_{SS}$ , and  $V^*$ . Use the square-law approximation (i.e.  $V_{od} = V^*$ ) and assume infinite transistor output resistance.



The solution is found by adjusting the output currents for zero output offset

$$I_{D1}R_{D1} = I_{D2}R_{D2}$$

This is equivalent to

$$\frac{\Delta I_D}{I_D} = \frac{\Delta R_D}{R_D}$$

Under this condition, assuming the offset voltage is small, the input voltage is given by

$$V_{os} = V_{GS1} - V_{GS2} = \Delta V_T + \frac{\Delta I_D}{g_m}$$

Substitution of the output trim condition yields

$$V_{os} = V_{GS1} - V_{GS2} = \Delta V_T + \frac{\Delta R_D}{R_D} \frac{I_D}{g_m}$$

or

$$V_{os} = V_{GS1} - V_{GS2} = \Delta V_T + \frac{\Delta R_D}{R_D} \frac{V^*}{2}$$

The variance of the offset voltage is therefore given by

$$\sigma_{V_{os}}^2 = \sigma_{V_{th}}^2 + \left(\frac{V^*}{2}\right)^2 \sigma_{\left(\frac{\Delta R}{R}\right)}^2$$

Reference:C:\Documents and Settings\Bernhard\My Documents\Lib\MathCAD\Default\defaults.mcd

# EECS 240, Spring 2004, Midterm Solution

#### <u>1) Noise</u>

$$S_{ieq} = 4 \cdot k_{B} \cdot T \cdot \gamma \cdot \frac{V_{1star}}{I_{SS}} \cdot \left(1 + 2 \cdot \frac{V_{1star}}{V_{5star}} + \frac{V_{1star}}{V_{9star}}\right)$$

(ignoring flicker noise)

### 2) Offset

- Systematic offset is result of different VDS of M9 and M10
- Solution: cascode M9 with a divice with same size and bias as M11. Make sure it won't go into triode (due to M9 diode connection).

3) Bandwidth  

$$g_{m1} = \frac{I_{SS}}{V_{1star}}$$

$$H(s) = \frac{C_s}{C_f} \cdot \frac{1 + s \cdot \frac{C_f}{g_{m1}}}{1 + \frac{s}{\omega_0}}$$

$$\omega_0 = F \frac{g_{m1}}{C_L + C_f \cdot (1 - F)}$$

$$F = \frac{C_f}{C_f + C_s + C_i}$$

usually the zero is at a much higher frequency than the pole and can be ignored.

$$H(s) = 1$$

$$\omega_{u} = \omega_{o} \cdot \left(\frac{C_{s}}{C_{f}} - 1\right) = \frac{g_{m1}}{C_{L} + C_{f} \cdot (1 - F)} \cdot \frac{C_{s}}{C_{f} + C_{s} + C_{i}}$$
(approx)

#### 4) Fast settling

Optimal settling for 2-pole response occurs for  $p_2 = -K\omega_0$  K = 3.3

$$p_2 = -\frac{g_{m7}}{C_{x1}}$$

$$C_{x1} = \frac{g_{m7}}{K \cdot \omega_{o}} = \frac{1}{K \cdot F} \cdot \frac{V_{1star}}{V_{7star}} \cdot C_{Leff}$$

### 5) Slewing

$$V_{1star} = V_{istep\_max} \cdot \frac{C_s}{C_s + C_a} \qquad C_a = C_i + ser(C_f, C_L)$$
$$V_{istep\_max} = V_{1star} \cdot \left(1 + \frac{C_a}{C_s}\right)$$
$$V_{istep\_max} = V_{1star} \cdot \frac{\left(C_f \cdot C_s + C_f \cdot C_i + C_L \cdot C_s + C_L \cdot C_i + C_f \cdot C_L\right)}{C_s \cdot \left(C_f + C_L\right)}$$

## 6) Slewing time

initial step at amplifier input:	$V_{x0} = V_{istep} \cdot \frac{C_s}{C_s + C_a}$
slew rate at output:	$SR_{o} = \frac{I_{SS}}{C_{c}}$ $C_{c} = C_{L} + ser(C_{f}, C_{s} + C_{i})$ $C_{c} = C_{L} + F \cdot (C_{s} + C_{i})$
slew rate at amp input:	$SR_i = F \cdot SR_o$
	$SR_i = F \cdot \frac{I_{SS}}{C_L + F \cdot (C_s + C_i)}$
slewing time:	$t_{slew} = \frac{V_{x0} - V_{1star}}{SR_i}$
	$t_{slew} = \frac{V_{x0} - V_{1star}}{I_{SS}} \cdot \left(\frac{C_L}{F} + C_s + C_i\right)$

Given

$$\begin{aligned} \mathbf{v}_{o} \cdot \mathbf{s} \cdot \left(\mathbf{C}_{f} + \mathbf{C}_{L}\right) - \mathbf{v}_{x} \cdot \left(\mathbf{s} \cdot \mathbf{C}_{f} + \mathbf{g}_{m}\right) &= 0 \\ \mathbf{v}_{x} \cdot \mathbf{C}_{T} - \mathbf{v}_{i} \cdot \mathbf{C}_{s} - \mathbf{v}_{o} \cdot \mathbf{C}_{f} &= 0 \end{aligned}$$

$$Find(\mathbf{v}_{o}, \mathbf{v}_{x}) \rightarrow \begin{bmatrix} -\mathbf{v}_{i} \cdot \mathbf{C}_{s} \cdot \frac{\left(\mathbf{s} \cdot \mathbf{C}_{f} + \mathbf{g}_{m}\right)}{\left(-\mathbf{s} \cdot \mathbf{C}_{f} \cdot \mathbf{C}_{T} - \mathbf{s} \cdot \mathbf{C}_{L} \cdot \mathbf{C}_{T} + \mathbf{s} \cdot \mathbf{C}_{f}^{2} + \mathbf{g}_{m} \cdot \mathbf{C}_{f}\right)} \\ -\mathbf{s} \cdot \mathbf{v}_{i} \cdot \mathbf{C}_{s} \cdot \frac{\left(\mathbf{C}_{f} + \mathbf{C}_{L}\right)}{\left(-\mathbf{s} \cdot \mathbf{C}_{f} \cdot \mathbf{C}_{T} - \mathbf{s} \cdot \mathbf{C}_{L} \cdot \mathbf{C}_{T} + \mathbf{s} \cdot \mathbf{C}_{f}^{2} + \mathbf{g}_{m} \cdot \mathbf{C}_{f}\right)} \end{bmatrix}$$

$$v_{o} = -v_{i} \cdot \frac{C_{s}}{C_{f}} \cdot \frac{1 + s \cdot \frac{C_{f}}{g_{m}}}{1 - s \cdot \frac{C_{f} \cdot C_{T} + C_{L} \cdot C_{T} - C_{f}^{2}}{g_{m} \cdot C_{f}}}$$

$$\frac{C_{f} \cdot C_{T} + C_{L} \cdot C_{T} - C_{f}^{2}}{g_{m} \cdot C_{f}} = \frac{C_{T} + \frac{C_{L}}{F} - C_{f}}{g_{m}} = \frac{C_{L}}{F \cdot g_{m}} \cdot \left(\frac{C_{T} \cdot F}{C_{L}} - C_{f} \cdot \frac{F}{C_{L}} + 1\right)$$

usually the zero is at much higher frequency than the pole --> ignore