

RECALL:

$$\bar{F} = F_{\min} + \frac{R_n}{G_s} |Y_s - Y_{\text{opt}}|^2$$

$$\left. \begin{array}{l} Y_{\text{opt}} \\ F_{\min} \\ R_n \end{array} \right\} \text{ FOUR PARAMETERS } \left\{ \begin{array}{l} \frac{v_n^2}{i_n^2} \\ Y_c \end{array} \right.$$

$$\text{LET } Y_s = Y_0 \frac{1 - \Gamma_s}{1 + \Gamma_s}$$

$$Y_{\text{opt}} = Y_0 \frac{1 - \Gamma_{\text{opt}}}{1 + \Gamma_{\text{opt}}}$$

$$|Y_s - Y_{\text{opt}}|^2 = \left| \frac{1 - \Gamma_s}{1 + \Gamma_s} - \frac{1 - \Gamma_{\text{opt}}}{1 + \Gamma_{\text{opt}}} \right|^2 Y_0^2$$

$$= \left(\frac{(1 - \Gamma_s)(1 + \Gamma_{\text{opt}}) - (1 - \Gamma_{\text{opt}})(1 + \Gamma_s)}{(1 + \Gamma_s)(1 + \Gamma_{\text{opt}})} \right)^2 Y_0^2$$

$$N = \frac{\cancel{1} - \Gamma_s + \cancel{1} \Gamma_{\text{opt}} - \cancel{1} \Gamma_{\text{opt}} + \cancel{1} \Gamma_s + \cancel{1} \Gamma_{\text{opt}}}{(1 + \Gamma_s)(1 + \Gamma_{\text{opt}})}$$

$$= 4 Y_0^2 \frac{|\Gamma_{\text{opt}} - \Gamma_s|^2}{(1 + \Gamma_s)^2 (1 + \Gamma_{\text{opt}})^2}$$

$$G_S = \operatorname{Re}(Y_S) = \frac{1}{2} Y_0 (Y_S + \overline{Y_S})$$

$$= \frac{1}{2} Y_0 \left(\frac{1 - \Gamma_S}{1 + \Gamma_S} + \frac{1 - \overline{\Gamma_S}}{1 + \overline{\Gamma_S}} \right)$$

$$= \frac{1}{2} Y_0 \frac{(1 - \Gamma_S)(1 + \overline{\Gamma_S}) + (1 - \overline{\Gamma_S})(1 + \Gamma_S)}{(1 + \Gamma_S)^2}$$

$$= \frac{1}{2} Y_0 \frac{(1 - \Gamma_S + \overline{\Gamma_S} - \Gamma_S \overline{\Gamma_S}) + (1 - \overline{\Gamma_S} + \Gamma_S - \overline{\Gamma_S} \Gamma_S)}{(1 + \Gamma_S)^2}$$

$$= Y_0 \frac{1 - |\Gamma_S|^2}{|1 + \Gamma_S|^2}$$

$$F = F_{\min} + \frac{R_n}{Y_0 \frac{(1 - |\Gamma_S|^2)}{(1 + \Gamma_S)^2}} \cdot \frac{4 Y_0^2 |\Gamma_{\text{opt}} - \Gamma_S|^2}{(1 + \Gamma_S)^2 (1 + \Gamma_{\text{opt}})^2}$$

$$F = F_{\min} + \frac{4 R_n Y_0 |\Gamma_{\text{opt}} - \Gamma_S|^2}{(1 - |\Gamma_S|^2) (1 + \Gamma_{\text{opt}})^2}$$

FOR FIXED F , THIS IS AN EQ FOR A CIRCLE OF Γ_S PLANE.

$$N = \text{NOISE FIG PARAM} = \frac{|\Gamma_S - \Gamma_{opt}|^2}{1 - |\Gamma_S|^2}$$

$$= \frac{F - F_{min}}{AR_n \gamma_0} \underbrace{|1 + \Gamma_{opt}|^2}_{\substack{\text{FOR FIXED } F \\ \text{THIS IS CONSTANT}}}$$

$$(\Gamma_S - \Gamma_{opt})(\bar{\Gamma}_S - \bar{\Gamma}_{opt}) = N(1 - |\Gamma_S|^2)$$

$$\Gamma_S \bar{\Gamma}_S - (\Gamma_{opt} \bar{\Gamma}_S + \bar{\Gamma}_{opt} \Gamma_S) - \Gamma_{opt} \bar{\Gamma}_{opt} = N(1 - |\Gamma_S|^2)$$

$$\Gamma_S \bar{\Gamma}_S (N+1) - \frac{x}{(N+1)} - \frac{\Gamma_{opt} \bar{\Gamma}_{opt} - N}{N+1} = 0$$

$$\Gamma_S \bar{\Gamma}_S - \frac{(\Gamma_S \bar{\Gamma}_{opt} + \bar{\Gamma}_{opt} \Gamma_S)}{N+1} + \frac{\Gamma_{opt} \bar{\Gamma}_{opt}}{(N+1)^2} = \frac{(\Gamma_{opt})^2 - N}{N+1} +$$

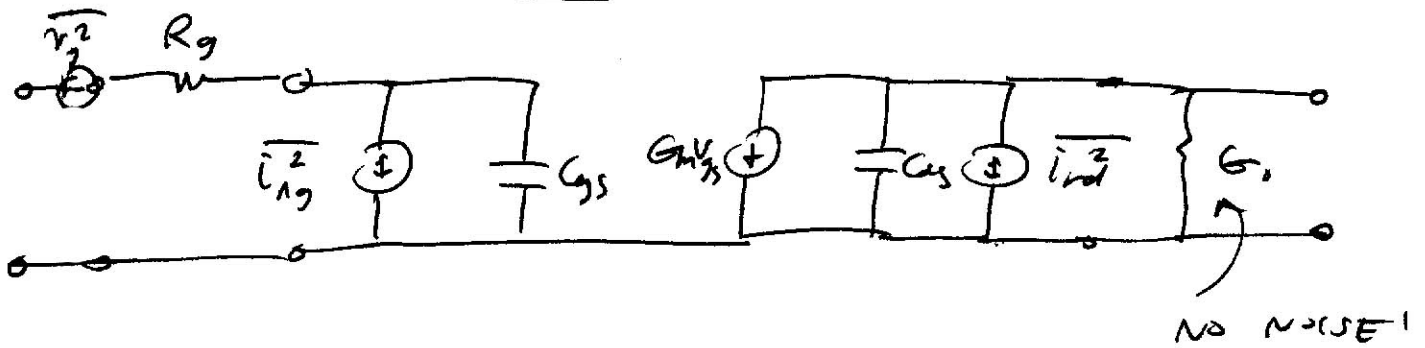
~~$$x^2 + \alpha^2 y^2 +$$~~

$$(x + \alpha y) = x^2 + \alpha^2 y^2 + 2\alpha xy \quad \frac{(\Gamma_{opt})^2}{(N+1)^2}$$

$$\left| \Gamma_S - \frac{\Gamma_{opt}}{N+1} \right| = \frac{\sqrt{N(N+1 - |\Gamma_{opt}|^2)}}{N+1}$$

(CENTER)
(RADIUS)

FET NOISE MODEL



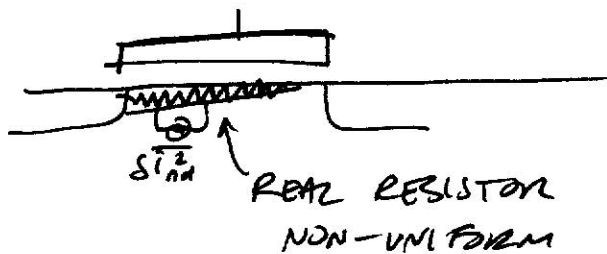
$$\overline{i_{Ng}^2} = 4KT \delta \frac{\omega^2 C_{gs}^2}{5g_{do}}$$

$$\overline{i_{nd}^2} = 4KT \delta g_{do} \quad \delta \approx \frac{2}{3} - 1.33$$

$$\delta \sim 1.33 - 4$$

$$C = \frac{\langle i_{Ng}, i_{nd} \rangle}{\sqrt{\overline{i_{Ng}^2} \overline{i_{nd}^2}}} \approx j 0.4 \quad \text{LONG CH. NOS CALC}$$

WHERE DOES NOISE COME FROM?



g_{do} IS CHANNEL CONDUCTANCE

$$g_{do} \propto \frac{I_{ds}}{V_{dsat}} \approx \frac{\frac{1}{2} \mu C_{ox} \left(\frac{W}{L}\right) (V_{gs} - V_t)^2}{V_{gs} - V_t}$$

$$= \frac{1}{2} g_m$$

WHEN DEVICE IS IN TRIODE : (V_{DS} SMALL)

$$I_D = \mu_{COX} \left(\frac{W}{L} \right) \left((V_{GS} - V_T) V_{DS} - \frac{V_{DS}^2}{2} \right)$$

$$g_{do} = \frac{\partial I_D}{\partial V_{DS}} \approx \mu_{COX} \left(\frac{W}{L} \right) (V_{GS} - V_T)$$

IN SATURATION:

$$I_D = \mu_{COX} \left(\frac{W}{L} \right) \frac{1}{2} (V_{GS} - V_T)^2$$

$$g_m = \frac{\partial I_D}{\partial V_{GS}} = \mu_{COX} \left(\frac{W}{L} \right) (V_{GS} - V_T)$$

$$g_m \approx g_{do}$$

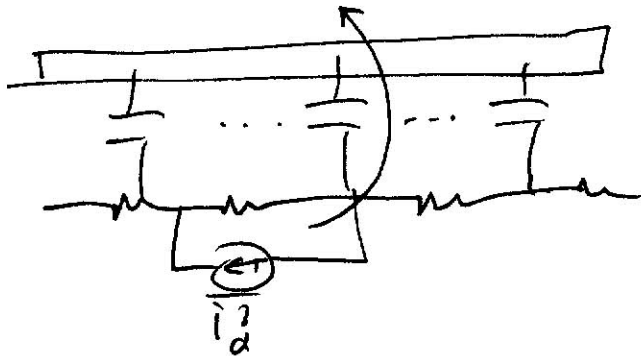
IN REALITY $\alpha \triangleq \frac{g_m}{g_{do}}$ DROPS SINCE

$$g_m = f(V_{GS}, V_{DS})$$

THERMAL NOISE $\propto G_{CH} \propto g_{do} \propto g_m$

$$\begin{aligned} \overline{v_d^2} &= 4kT \int g_{do} = 4kT \int \frac{g_m}{\alpha} \\ &= 4kT \left(\frac{\int}{\alpha} \right) g_m \end{aligned}$$

WHERE DOES GATE NOISE COME FROM?



DRAIN NOISE LEAKS INTO GATE THROUGH C_{gs} . AS FREQ INCREASES, THIS GATE CURRENT INCREASES. GATE CURRENT IS THIS CORRELATED TO DRAIN NOISE:

$$\frac{\overline{i_{ng}^2}}{\Delta f} = 4kT \delta \frac{\omega^2 C_{gs}^2}{5 g_{d0}} \quad \left| \quad \langle i_{ng}, i_{nd} \rangle = \frac{1}{6} \omega C_{gs}$$

EQUIV GATE NOISE VOLTAGE

$$\frac{\overline{V_n^2}}{\Delta f} = 4kT R_{eq}$$

$$R_{eq} \stackrel{?}{=} \text{INPUT RESISTANCE}$$

$$= \frac{1}{5} \frac{1}{g_m}$$

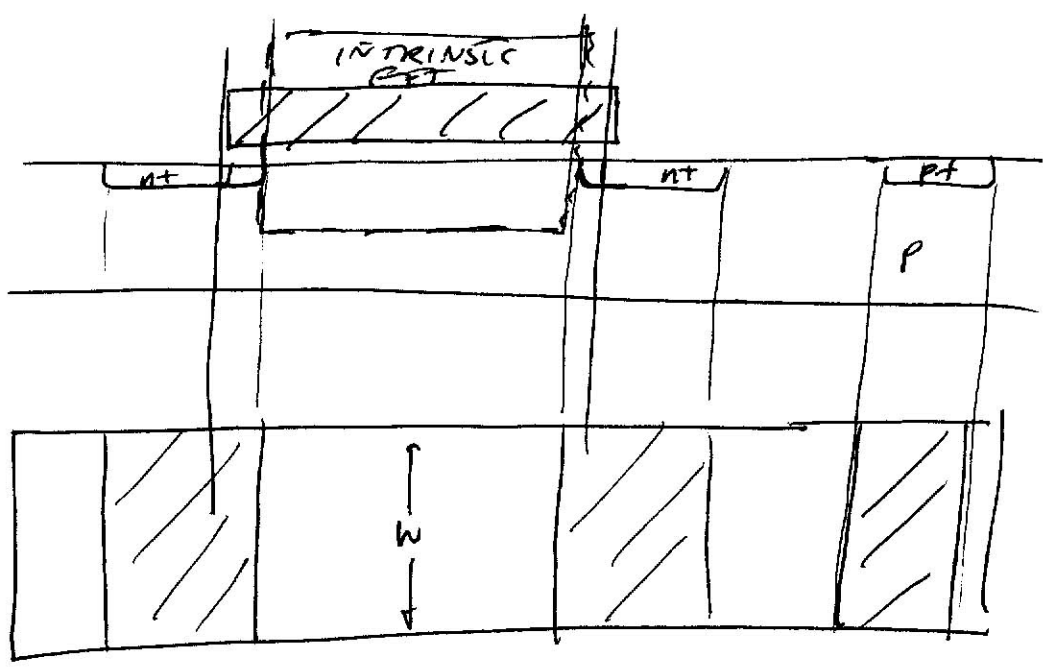
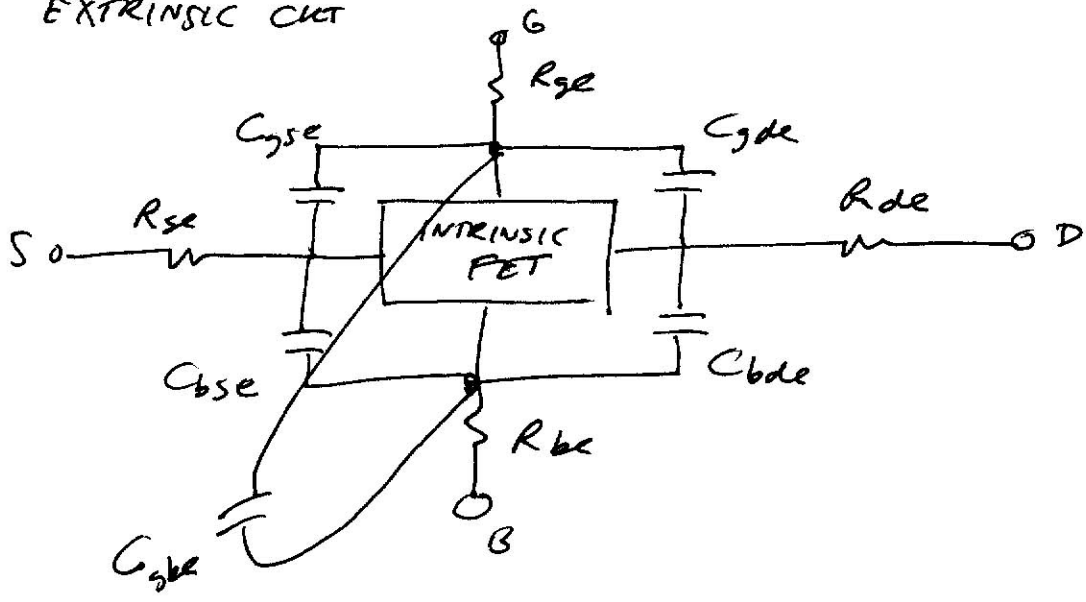
ACTUAL VALUE IS $\frac{4}{3} R_i$

↑ CLOSE TO 1!

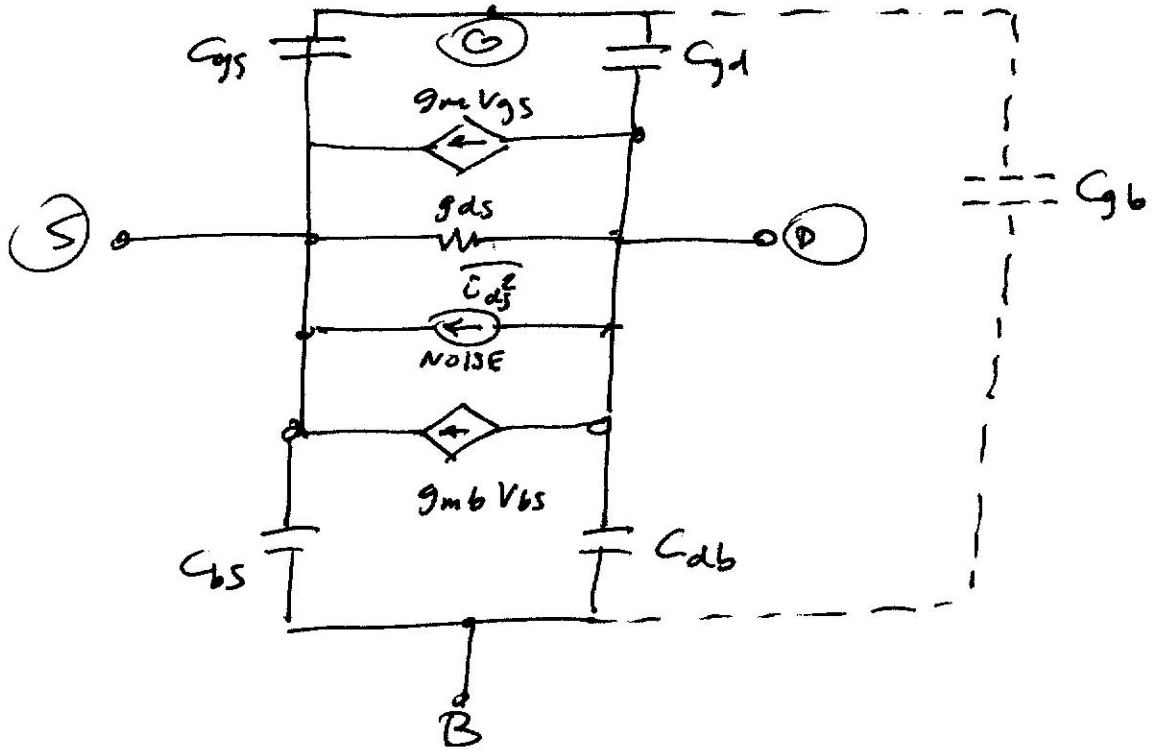
SMALL SIGNAL EQ CIRCUIT FOR FETS

MEDIUM FREQ (RF) 4 TERMINAL DEVICE

EXTRINSIC CKT



SIMPLE INTRINSIC MODEL (QUASI-STATIC)



NOISE : IN SAT

$$\overline{C_{ds}^2} = 4KT \left[\frac{2}{3} \underbrace{\frac{w}{L} \mu C_{ox} (V_{GS} - V_T)}_{g_{sd0}} \right]$$

$\gamma = \frac{2}{3}$

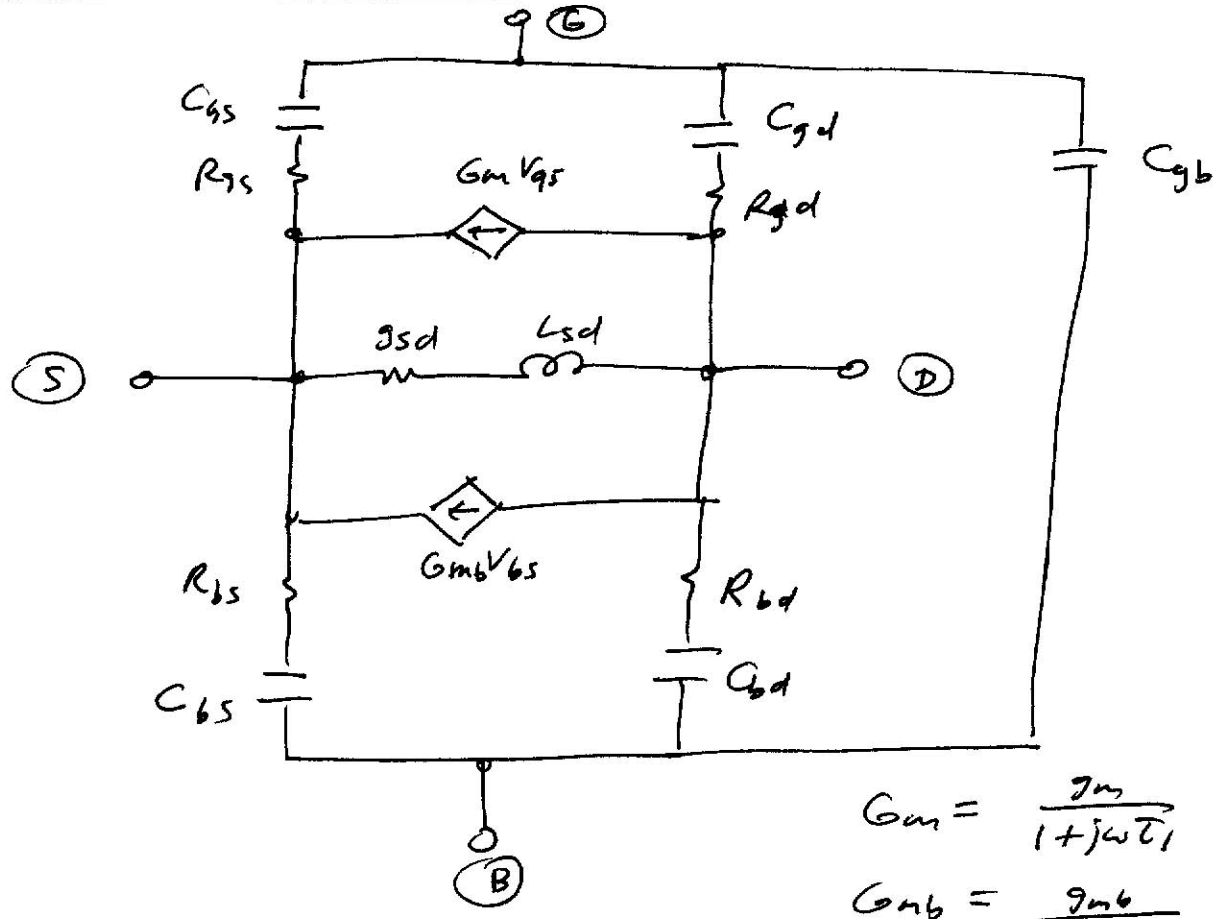
CH CONDUCTANCE FOR $V_{DS} = 0$

FOR SHORT CHANNEL DEVICES γ IS LARGER DUE TO DISTRIBUTED EFFECTS. HOT ELECTRON EFFECTS MAY ALSO CONTRIBUTE $\gamma \sim 2-3$ REPORTED.

INPUT REFER NOISE : $\overline{V_n^2} = \frac{\overline{C_{ds}^2}}{g_m^2}$

FLICKER NOISE : LF NOISE IMPEDANCE ^{ESP. FOR} OSCILLATORS DUE TO NOISE UP-CONVERSION

NON-QUASI-STATIC MODEL (BSIM3 MOS TRANSISTOR)



$$G_m = \frac{g_m}{1 + j\omega\tau_1}$$

$$G_{mb} = \frac{g_{mb}}{1 + j\omega\tau_1}$$

$$L_{sd} g_{sd} = \tau_1$$

IN SATURATION THIS MODEL SIMPLIFIED TO

$$C_{gs} = \frac{2}{3} C_{ox}$$

$$R_{gs} = \frac{1}{5g_m}$$

$$R_{bs} = \frac{1}{(\alpha - 1)g_{m5}}$$

$$C_{bs} = (\alpha - 1) \frac{2}{3} C_{ox}$$

$$C_{gb} = \frac{\alpha - 1}{3\alpha} C_{ox}$$

$$\tau_1 \approx \frac{1}{3.75\omega_0}$$

$$\omega_0 = \frac{\mu(V_{gs} - V_{th})}{\alpha L^2}$$

$$\alpha \approx 1 + \frac{\gamma}{2\sqrt{\phi_0 + V_{sb}}}$$

SP (IN STRONG) (MV)

BODY EFFECT COEFF (MV)

MODEL VALID $\approx \omega_0$

NOTE $\omega_0 = \omega_T$ (NO VELOCITY SAT)

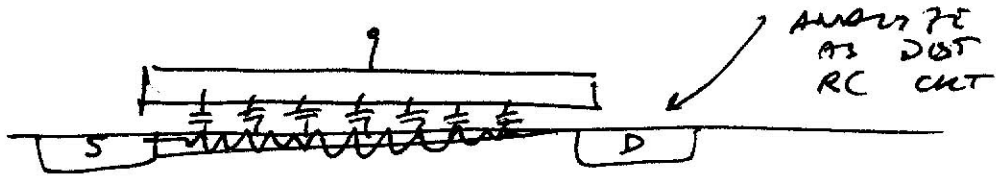
$\omega_T = \frac{|v_d|_{max}}{L}$ VELOCITY SAT.

E.G. $|v_d|_{max} \approx 10^7$ cm/s

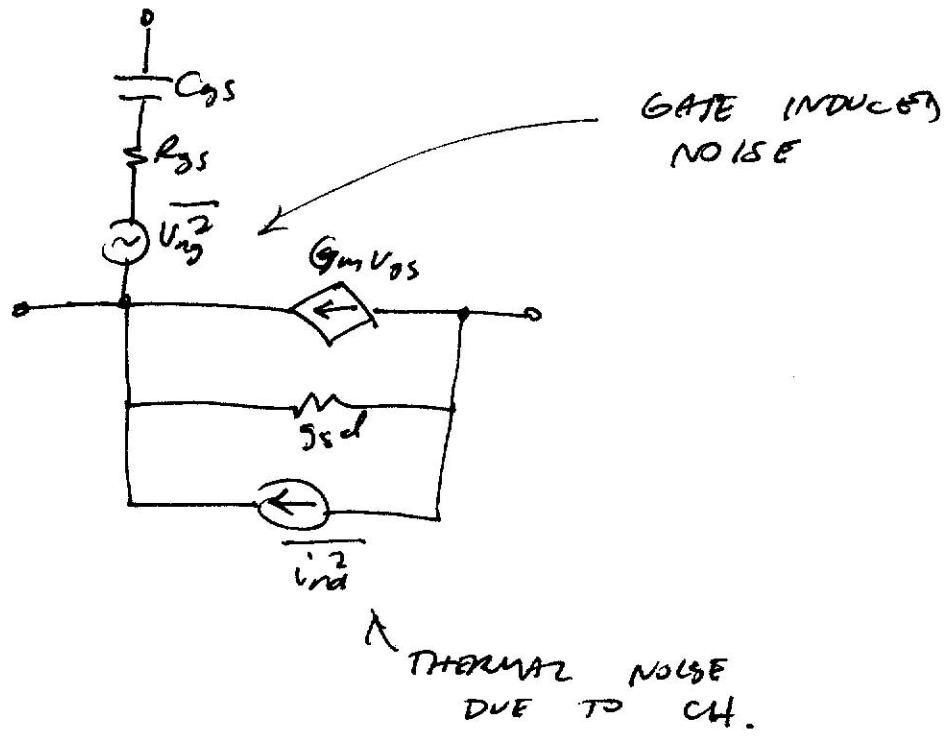
$L \approx 0.1 \mu$

$\rightarrow \omega_T = 160 \text{ GHz} \times 2\pi$

CHANNEL RESISTANCE PLAYS AN IMPORTANT ROLE IN NON-QUASI-STATIC MODEL



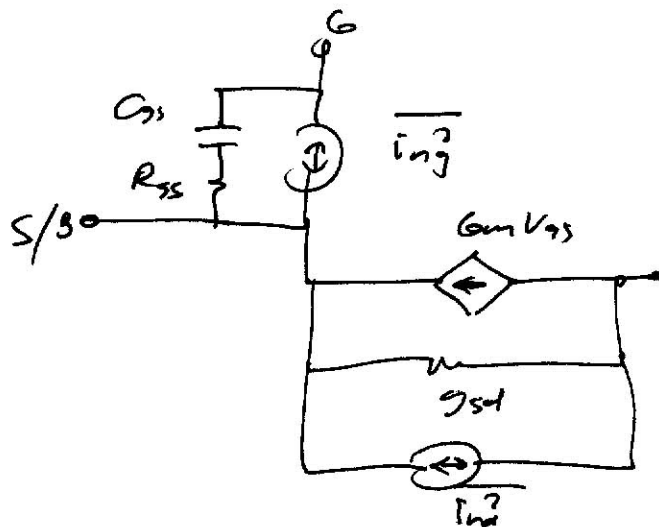
NOISE



$$\overline{v_{ng}^2} = 4KT \left(\frac{4}{3} R_{gs} \right)$$

INTUITIVE RESULTS
IS $4KT R_{gs}$

COMMON-WAY IS TO REPRESENT AS NORTON EQ.



$$\overline{i_{ng}^2} = 4KT \left(\frac{4}{3} R_{gs} \right) \omega^2 C_{gs}^2$$

THIS NOISE IS CORRELATED WITH THE DRAIN NOISE

$$\langle \overline{i_{ng}}, \overline{i_{nd}} \rangle = 4KT \frac{1}{6} j\omega C_{gs}$$